

Convergence analysis of CMA-ES

ISMP 2024

Stochastic DFO 1

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polytechnique

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Inria



Find $x^* \in \underset{x \in \mathbb{R}^d}{\text{Arg min}} f(x)$ (P)

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Covariance Matrix Adaptation-ES (CMA-ES)

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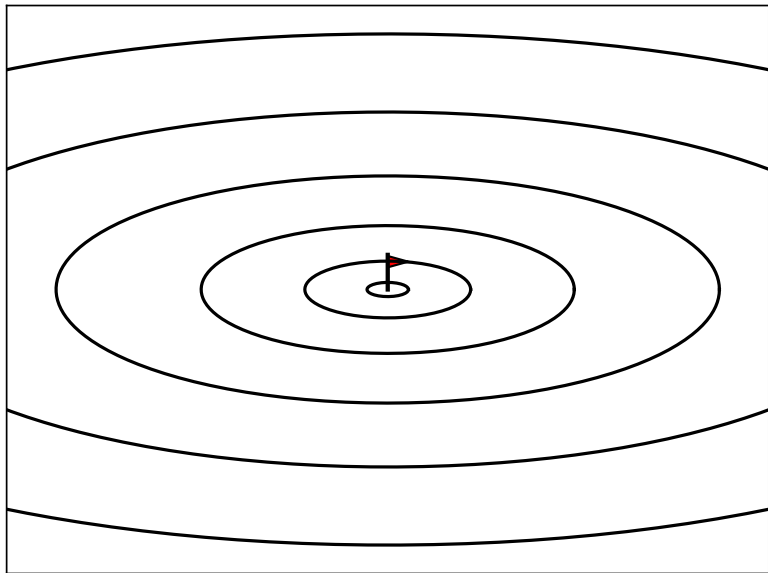
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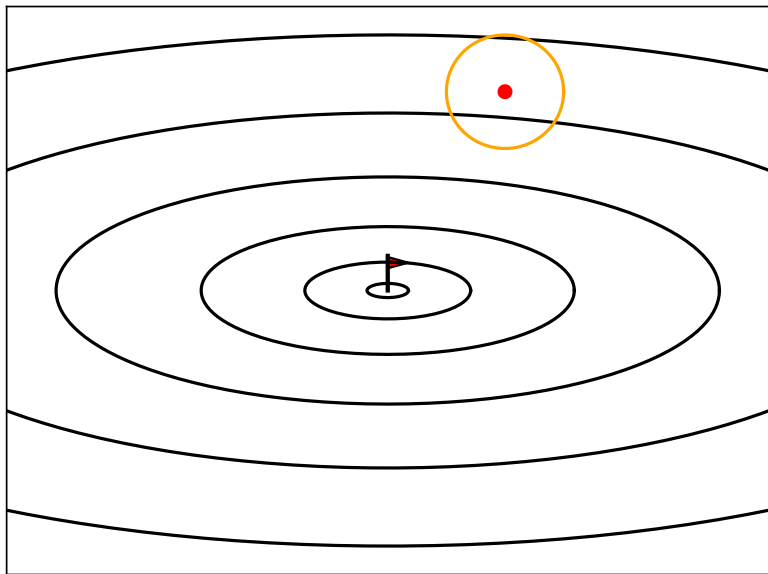
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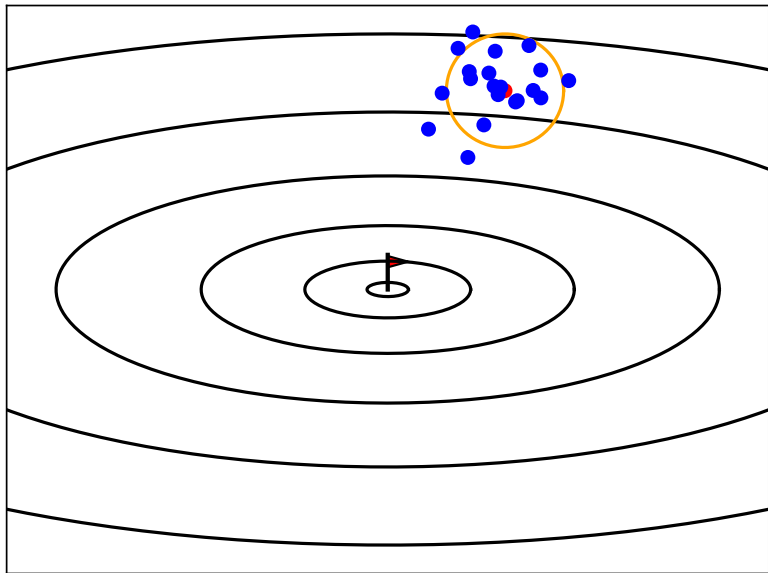
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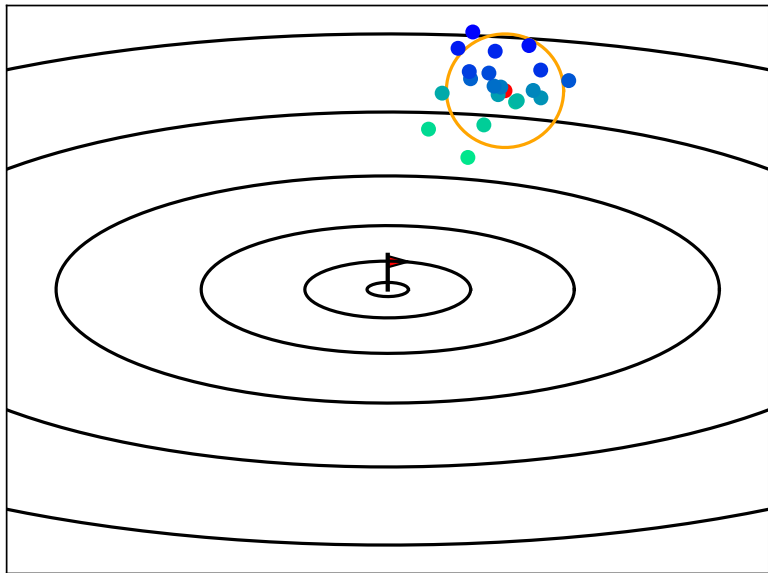
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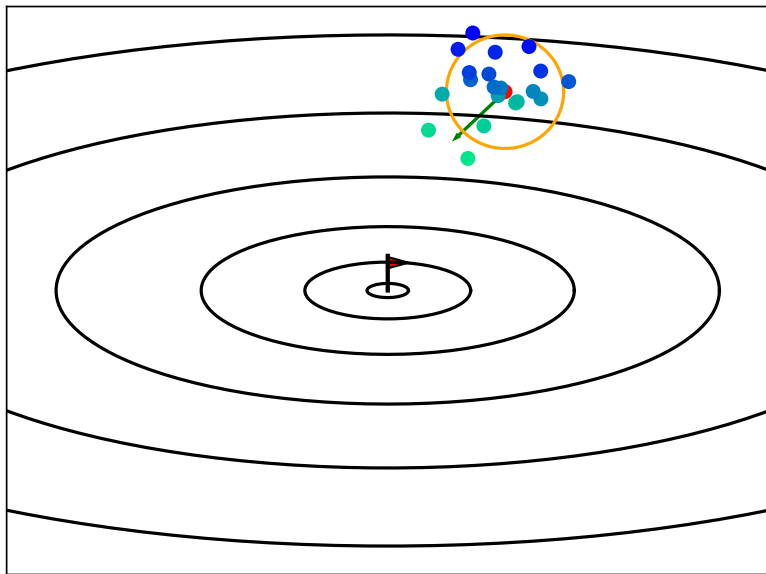
3. Update $\theta_{t+1} = (m_{t+1}, \sigma_{t+1}, \mathbf{C}_{t+1})$.

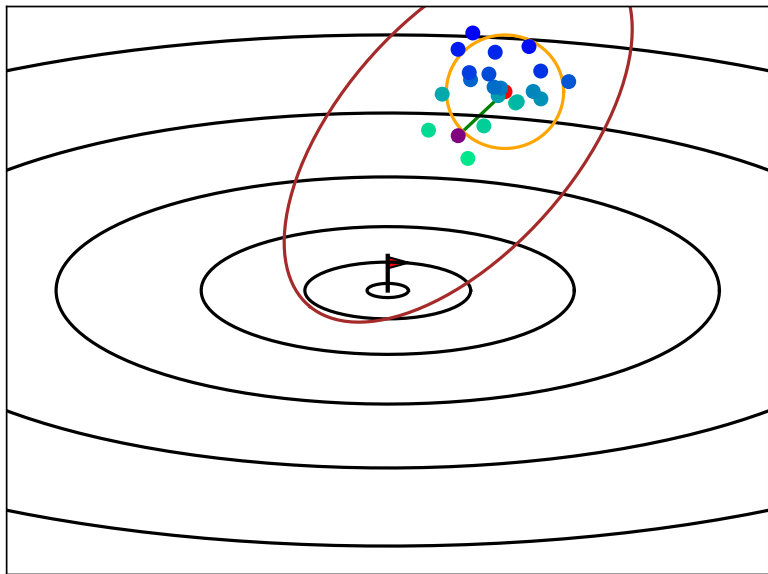












Mean update:

$$m_{t+1} = \text{Average}(x_{t+1}^{1:\lambda}, \dots, x_{t+1}^{\mu:\lambda})$$

Mean update:

$$\begin{aligned} m_{t+1} &= \text{Average}(x_{t+1}^{1:\lambda}, \dots, x_{t+1}^{\mu:\lambda}) \\ &= \sum_{i=1}^{\mu} \underbrace{\text{weight}_i}_{w_i} x_{t+1}^{i:\lambda} \end{aligned}$$

Step-size adaptation:

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Step-size adaptation:

$$\begin{aligned}\sigma_{t+1} &= \sigma_t \times \text{increasing function} (\|m_{t+1} - m_t\|) \\ &= \sigma_t \times \exp \left(\frac{1}{d_\sigma} \left(\frac{\|\sigma_t^{-1} \mathbf{C}_t^{-1/2} (m_{t+1} - m_t)\|}{\|\text{weights}\| \mathbb{E} \|\mathcal{N}\|} - 1 \right) \right)\end{aligned}$$

Covariance matrix adaptation:

$$\mathbf{C}_{t+1} = \text{Positive combination} \left(\mathbf{C}_t, \text{Average} \left[\overleftarrow{\left(x_{t+1}^{i:\lambda} - m_t \right)} \right] \right)$$

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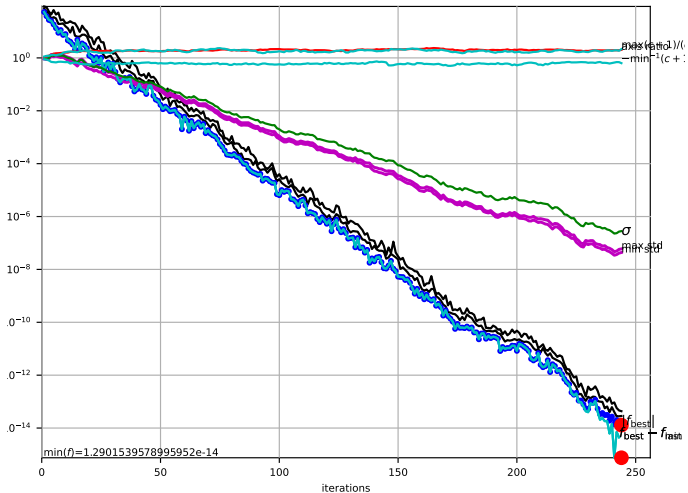
Covariance matrix adaptation:

$$\begin{aligned} \mathbf{C}_{t+1} &= \text{Positive combination} \left(\mathbf{C}_t, \text{Average} \left[\overleftarrow{\left(\mathbf{x}_{t+1}^{i:\lambda} - \mathbf{m}_t \right)} \right] \right) \\ &= (1 - c_\mu) \mathbf{C}_t \\ &\quad + \underbrace{\frac{c_\mu}{\sigma_t^2} \sum_{i=1}^{\mu} w_i (\mathbf{x}_{t+1}^{i:\lambda} - \mathbf{m}_t) (\mathbf{x}_{t+1}^{i:\lambda} - \mathbf{m}_t)^\top}_{\text{rank-mu update}} \end{aligned}$$

$$f(x) = \frac{1}{2}x^\top \mathbf{H}x$$

$$\text{Cond}(\mathbf{H}) = 10^0$$

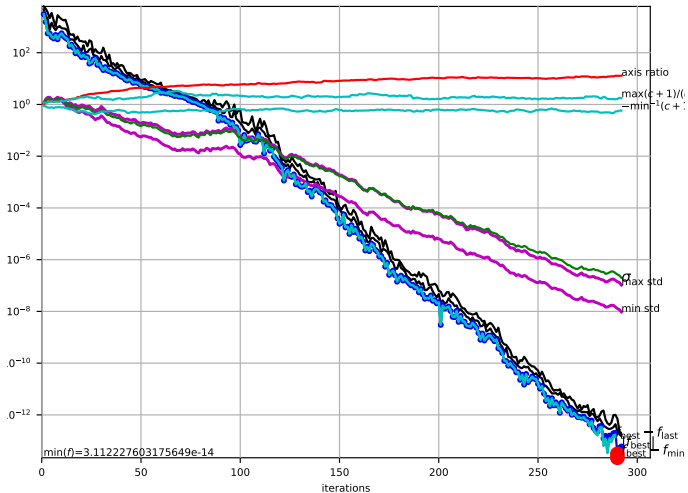
$|f_{\text{best, med, worst}}, f - \min(f), \sigma, \text{axis ratio}|$



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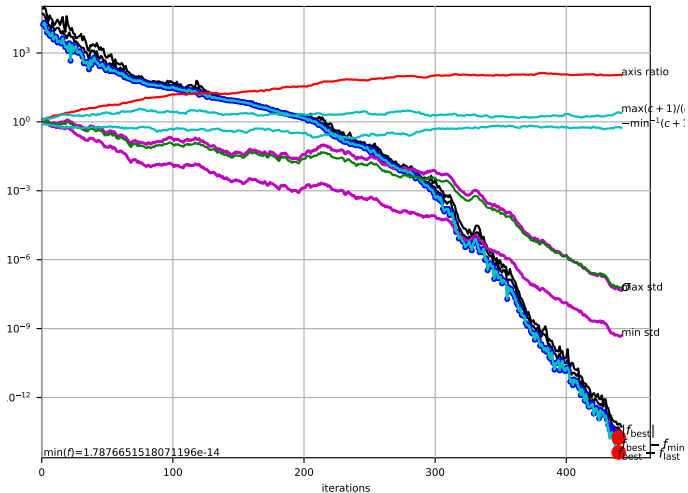
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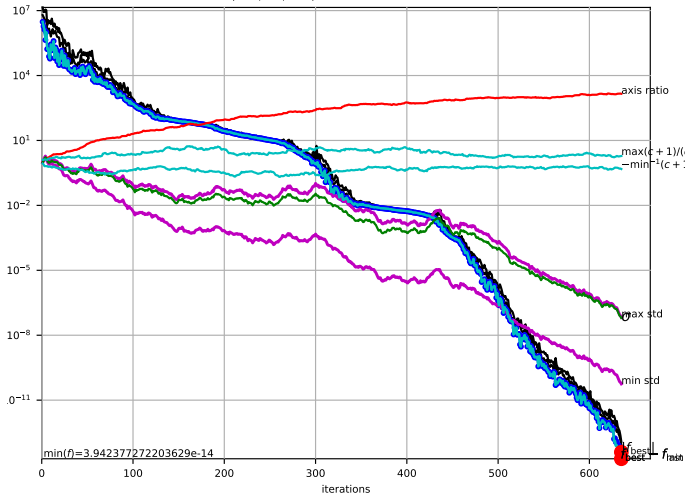
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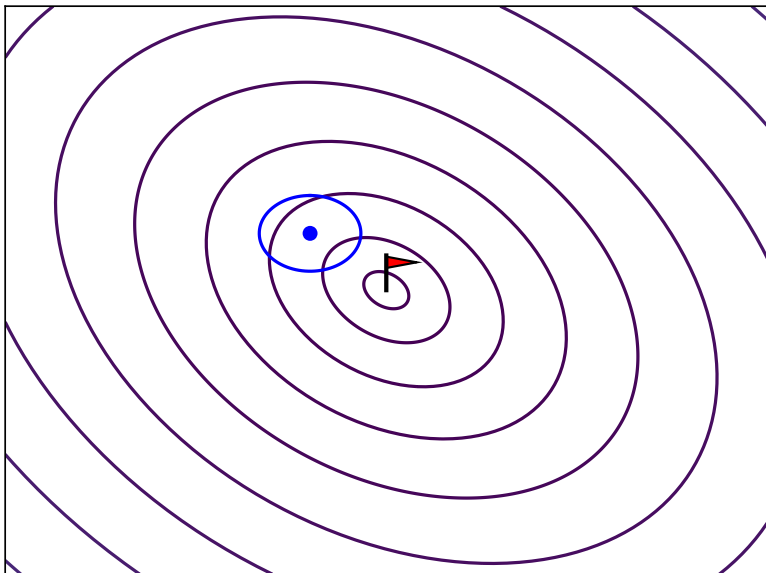


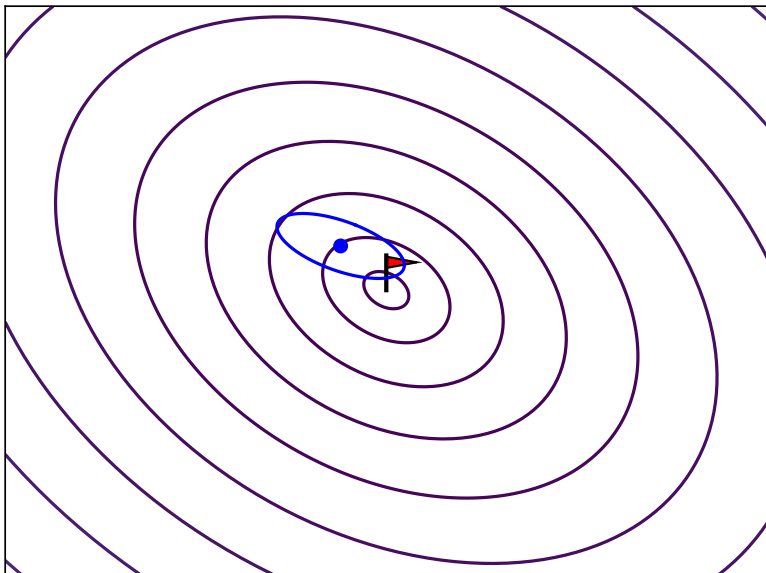
$$f(x) = \frac{1}{2}x^T \mathbf{H}x$$

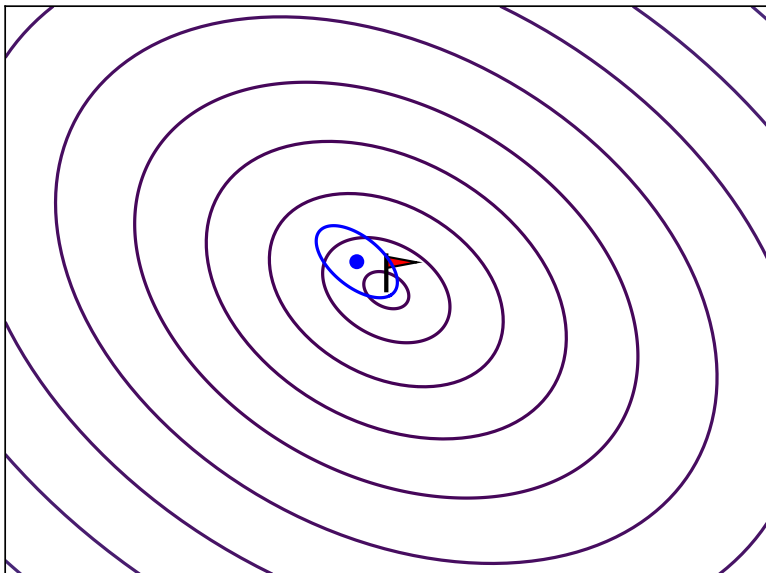
$$\text{Cond}(\mathbf{H}) = 10^6$$

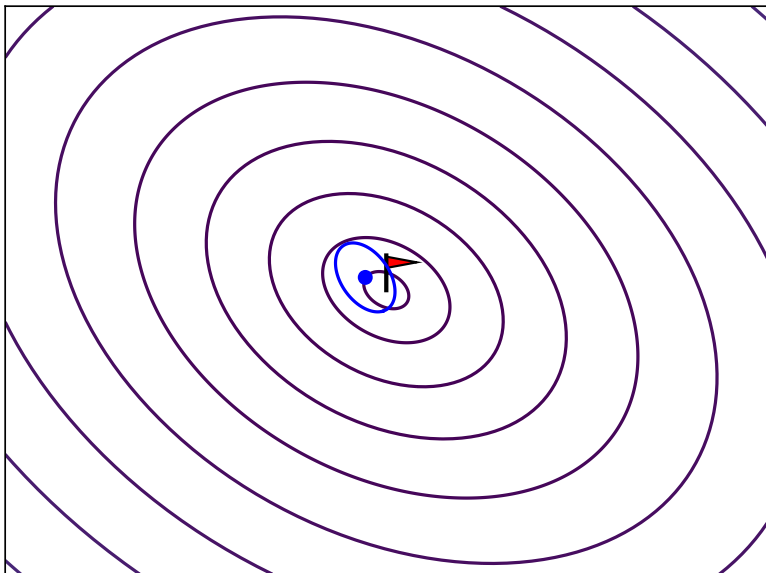
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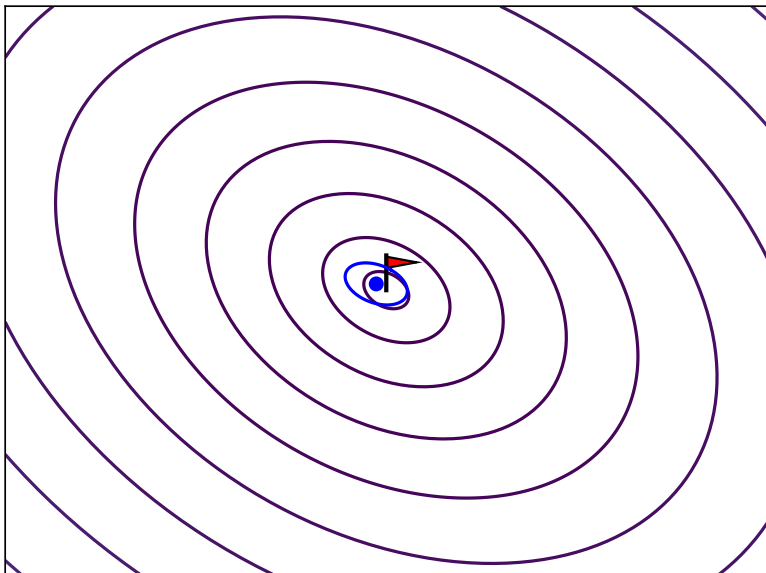


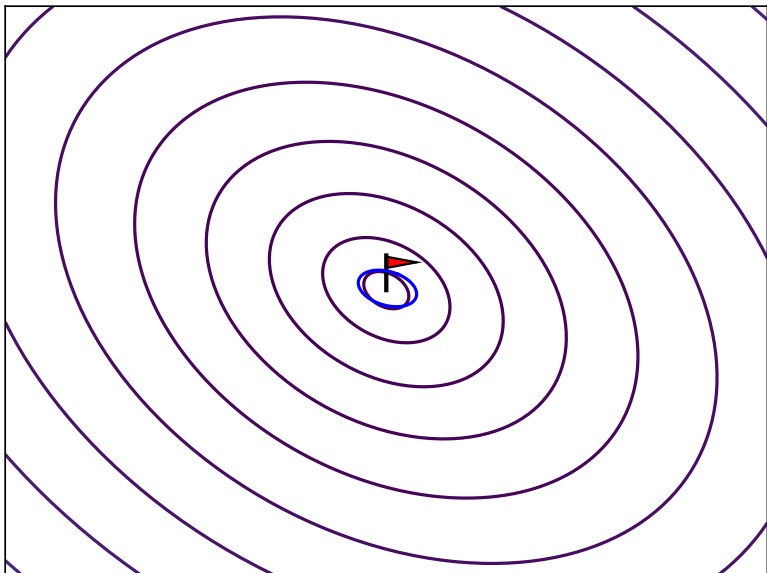


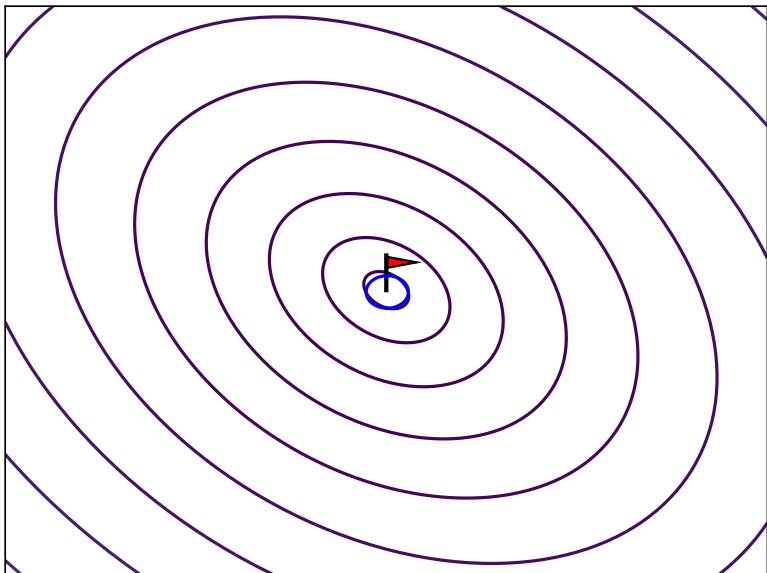


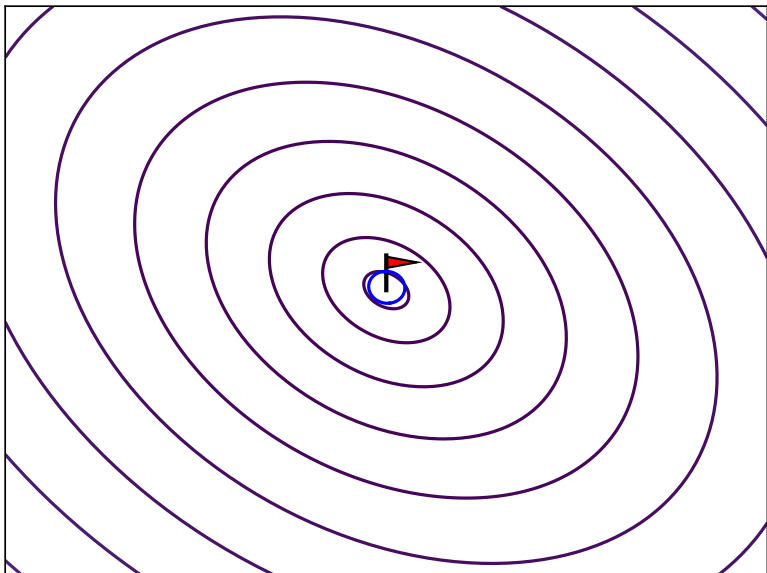


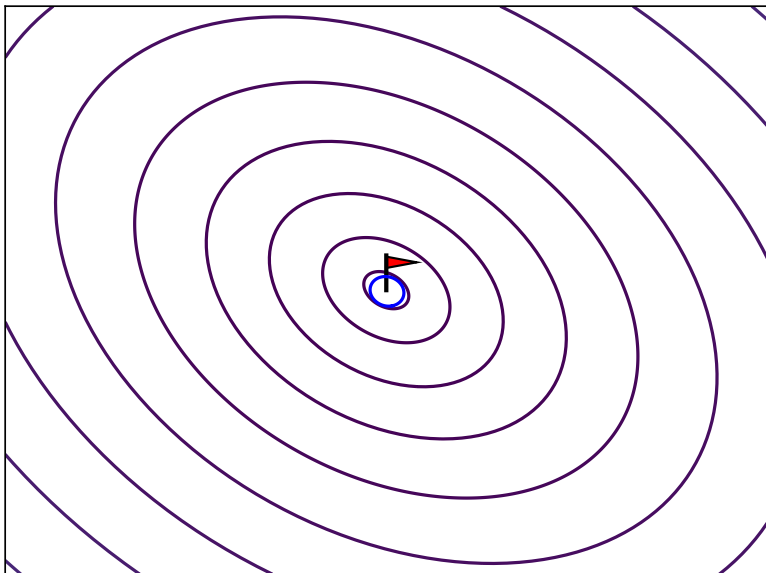


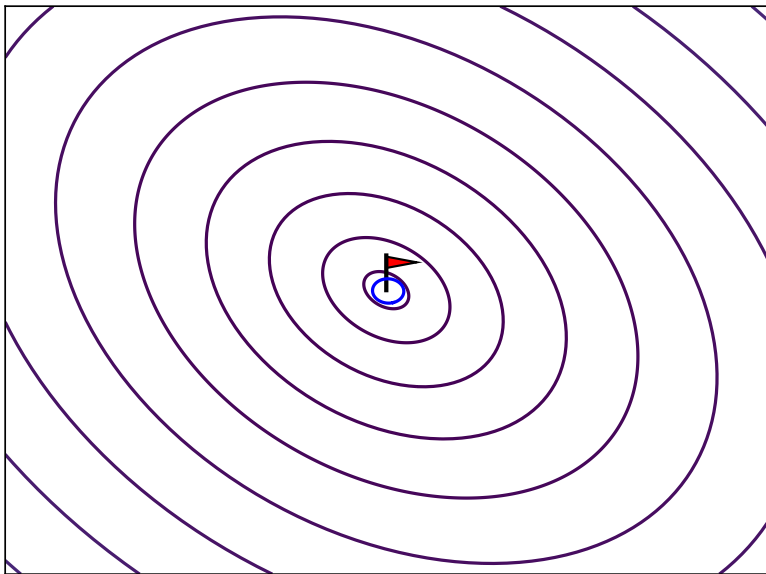


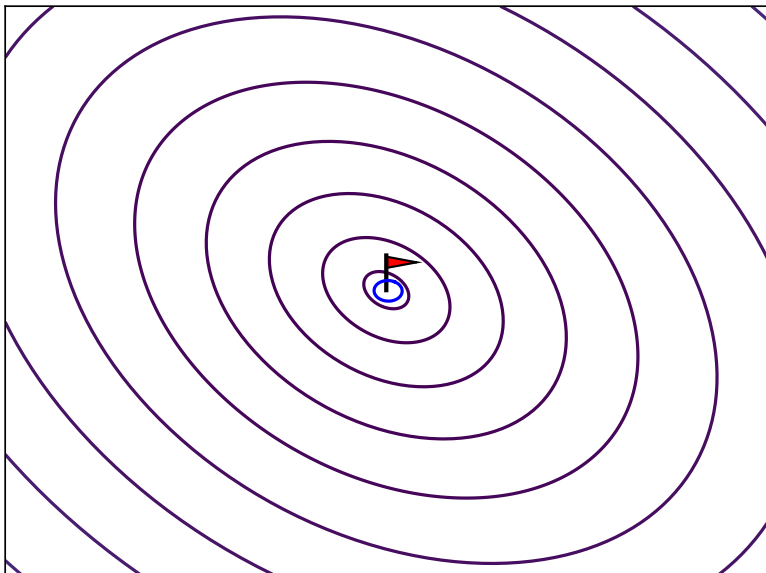


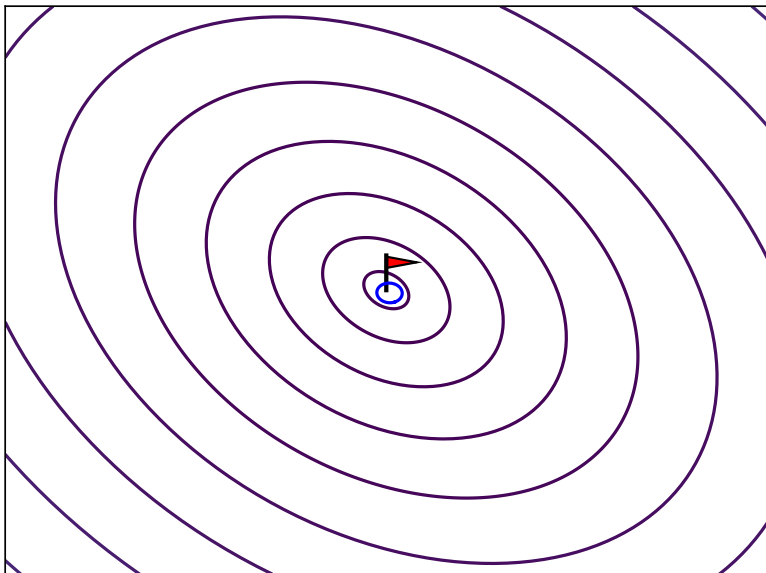


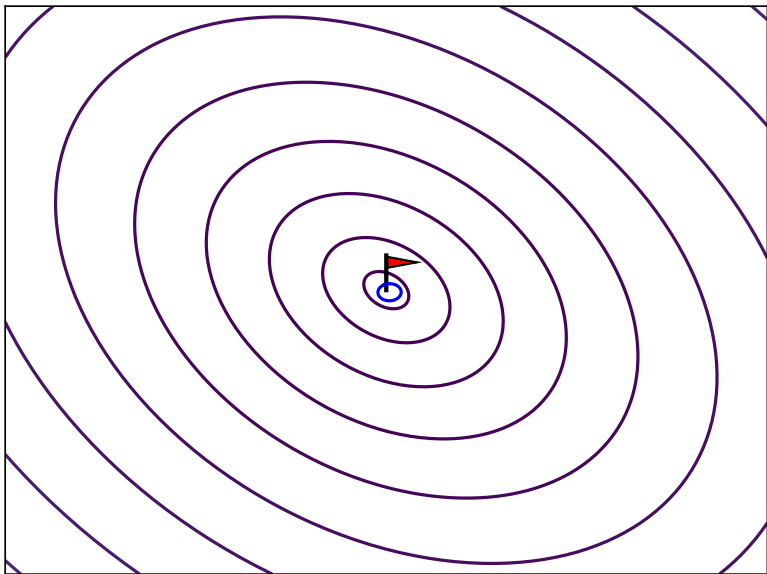


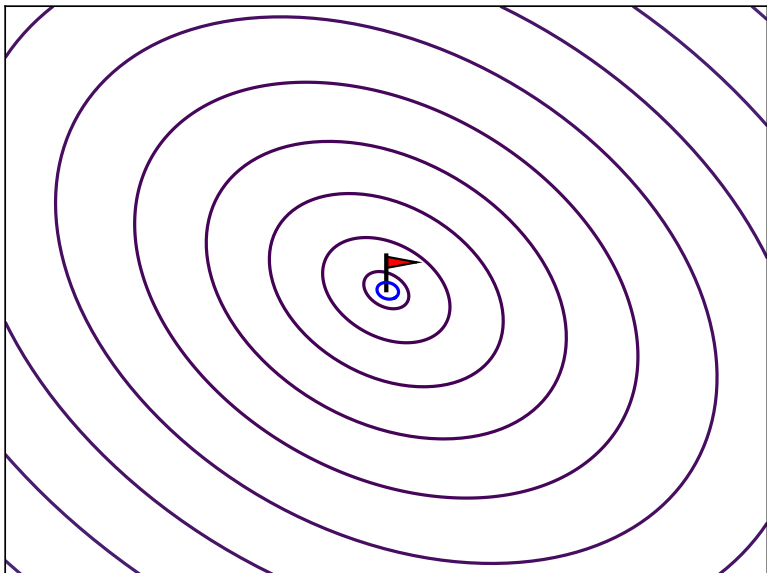


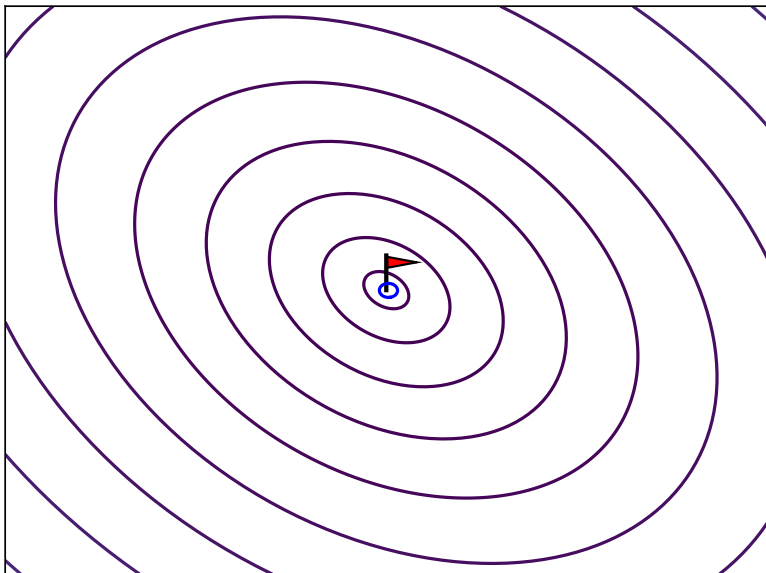


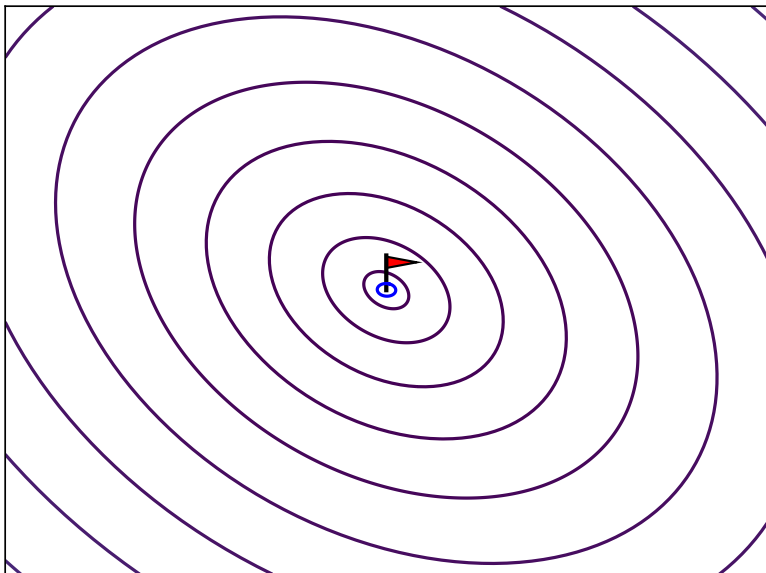


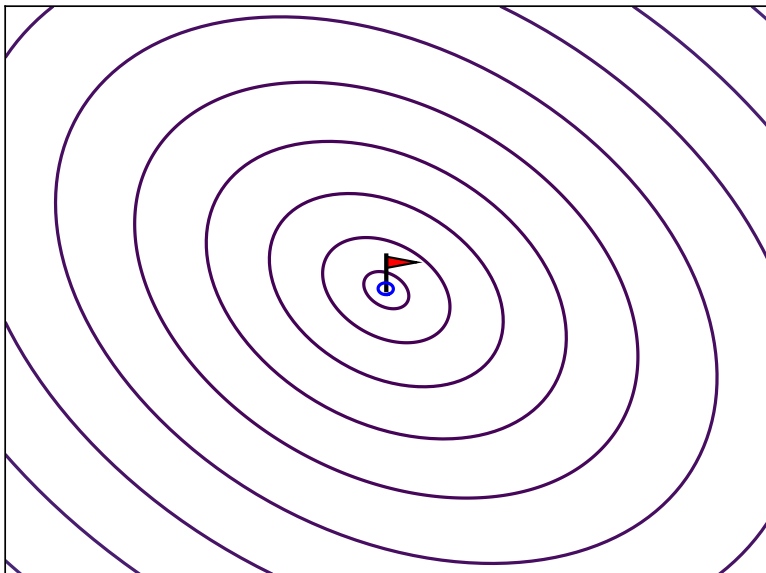


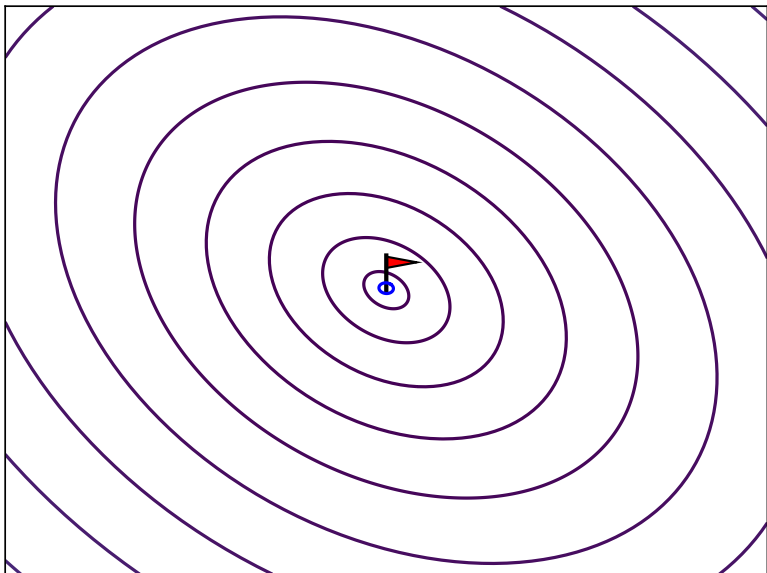






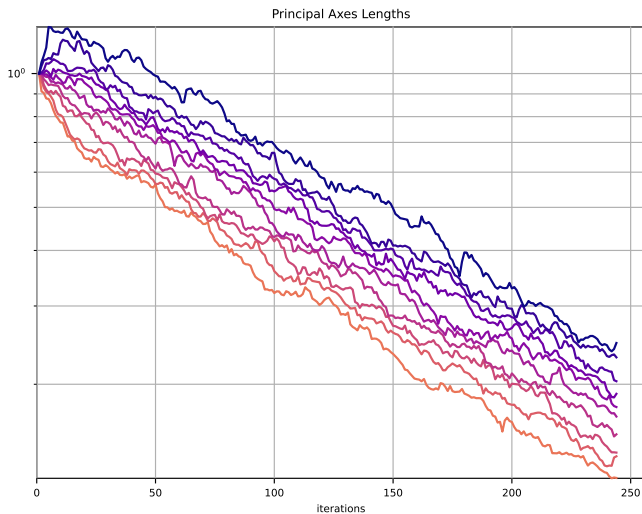






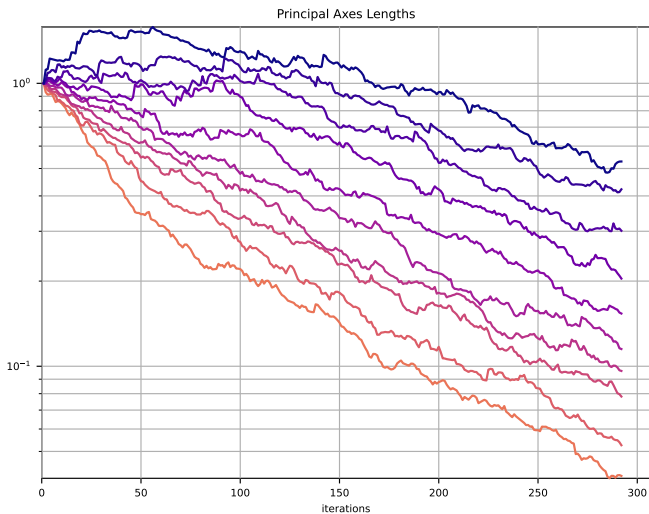
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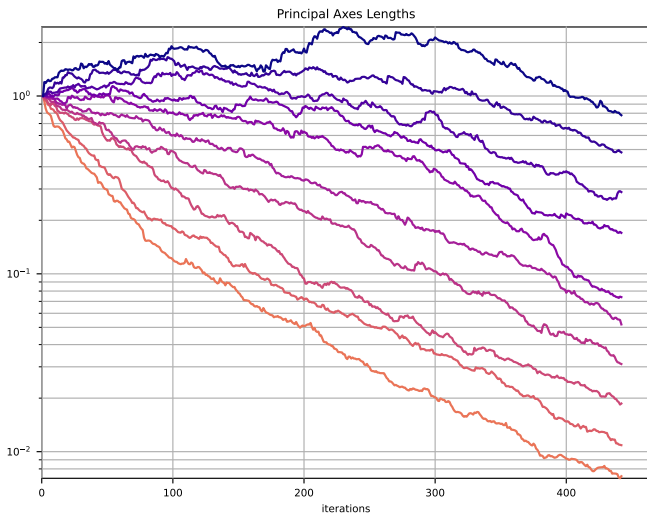
\mathbf{C}_t approximates \mathbf{H}^{-1} .

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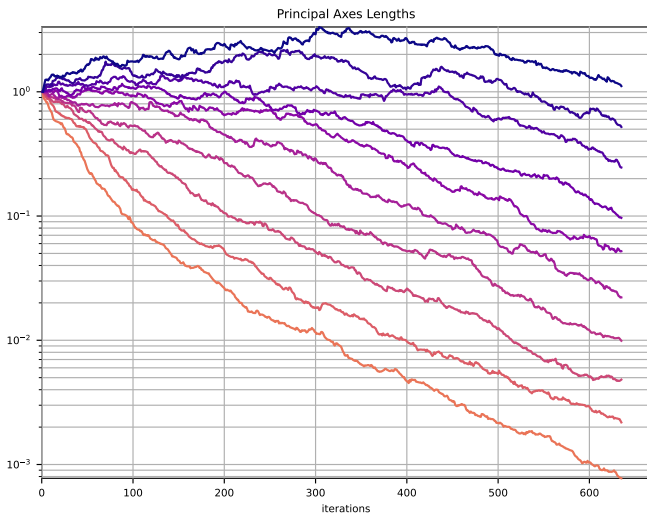
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 $f(x) = x^\top \mathbf{H}x/2$:

$$\lim_{t \rightarrow \infty} \mathbb{E} \left[\frac{\mathbf{C}_t}{\text{normalization}} \right] \propto \mathbf{H}^{-1}$$

Markov chains and transition kernels

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A **Markov chain** with transition kernel P is a random sequence $\{\theta_t\}_{t \in \mathbb{N}}$ such that:

$$\mathbb{P}[\theta_{t+1} \in A \mid \theta_t = x] = P(x, A).$$

Ergodic Markov chain

$$\text{If } \theta_0 \sim \nu_0$$

After k steps:

$$\theta_k \sim \nu_k = \nu_0 P^k = \int \nu_0(dx) P^k(x, \cdot)$$

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If

$$\exists \pi, \forall \nu_0, \quad \lim_{k \rightarrow \infty} \nu_k = \pi$$

then $\{\theta_k\}_{k \in \mathbb{N}}$ is **ergodic**.

Limit theorems

If $\{\theta_t\}_{t \in \mathbb{N}}$ is ergodic with limit law π :

$$\lim_{t \rightarrow \infty} \mathbb{E}[f(\theta_t)] = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} f(\theta_t) = \mathbb{E}_{\theta \sim \pi}[f(\theta)]$$

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3. Use limit theorems to prove linear convergence of $\{\theta_t\}_{t \in \mathbb{N}}$

This approach was successful for stepsize adaptive-ES

Definition of a normalized Markov chain for CMA-ES

In order to obtain a stationary Markov chain:

$$z_t = \frac{m_t - x^*}{\sigma_t \sqrt{\lambda_{\min}(\mathbf{C}_t)}}$$

$$\Sigma_t = \frac{\mathbf{C}_t}{\lambda_{\min}(\mathbf{C}_t)}$$

Proposition

If $f \in \left\{ \left[\text{contour plot 1} \right], \left[\text{contour plot 2} \right], \left[\text{contour plot 3} \right], \left[\text{contour plot 4} \right] \right\}$,¹ then $\{(z_t, \Sigma_t)\}_{t \in \mathbb{N}}$ is a Markov chain.

¹scaling-invariant functions

If $\{(z_t, \Sigma_t)\}_{t \in \mathbb{N}}$ is ergodic:

$$\frac{1}{T} \log \frac{\|m_T - x^*\|}{\|m_0 - x^*\|}$$

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$$\lim_{T \rightarrow \infty} \frac{1}{T} \log \frac{\|m_T - x^*\|}{\|m_0 - x^*\|} = \mathbb{E}_\pi[\log \|z\|] - \mathbb{E}_\pi[\log \|z\|] - \mathbb{E}_\pi \left[\log \frac{\sigma_1 \lambda_{\min}(\mathbf{C}_1)^{1/2}}{\sigma_0 \lambda_{\min}(\mathbf{C}_0)^{1/2}} \right]$$

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$$\|m_T - x^*\| \underset{T \rightarrow \infty}{\sim} e^{-T \mathbb{E}_\pi \left[\log \frac{\sigma_1 \lambda_{\min}(\mathbf{C}_1)^{1/2}}{\sigma_0 \lambda_{\min}(\mathbf{C}_0)^{1/2}} \right]} \|m_0 - x^*\|$$

$$\log \frac{\sigma_1}{\sigma_0} \propto \frac{\|\sum w_i z_1^{i:\lambda}\|}{\|\text{weights}\| \mathbb{E} \|\mathcal{N}\|} - 1$$

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We are able to prove

$$\mathbb{E}_\pi \left[\frac{\|\sum w_i z^{i:\lambda}\|^2}{\|\text{weights}\|^2 \mathbb{E}\|\mathcal{N}\|^2} - 1 \right] > 0$$

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(and under which conditions?)

How to prove that $\{\phi_t\}_{t \in \mathbb{N}}$ is ergodic

1. Irreducibility and aperiodicity of $\{\phi_t\}$
2. Drift condition:

$$\mathbb{E}[V(\phi_1)] \leq (1 - \varepsilon)V(\phi_0) \quad \forall \phi_0 \notin K$$

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Theorem

If 1. and 2. hold for a small set K , then $\{\phi_t\}$ is ergodic (V -geometrically ergodic).

1. Irreducibility and aperiodicity

$\{\phi_t\}_{t \in \mathbb{N}}$ is irreducible when

$$\forall \phi_{\text{start}}, \phi_{\text{end}} \in \Phi, \underbrace{\exists k > 0, \mathbb{P}[\phi_k = \phi_{\text{end}} \mid \phi_0 = \phi_{\text{start}}] > 0}_{\phi_{\text{start}} \rightsquigarrow \phi_{\text{end}}}$$

1. Irreducibility and aperiodicity

$\{\phi_t\}_{t \in \mathbb{N}}$ is irreducible when

$$\forall \phi_{\text{start}} \in \Phi, \forall \Phi_{\text{end}} \subset \Phi, \text{Volume}(\Phi_{\text{end}}) > 0 \Rightarrow \phi_{\text{start}} \rightsquigarrow \Phi_{\text{end}}$$

1. Irreducibility and aperiodicity

Theorem*

The Markov chain

$$\phi_{t+1} = F(\phi_t, U_{t+1})$$

is irreducible and aperiodic when

- (i) *there exists a **steadily attracting state** ϕ^* ;*
- (ii) *there exists a path U_1^*, \dots, U_k^* at which $F^k(\phi^*, \cdot)$ is **submersive**.*

Assumptions: F is loc. Lipschitz and $U_{t+1} \sim p_{\phi_t}$ where $(\phi, u) \mapsto p_{\phi}(u)$ is lsc

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For us:

$$(z_{t+1}, \Sigma_{t+1}) = F((z_t, \Sigma_t), z_{t+1}^{i:\lambda})$$

Assumptions: F is loc. Lipschitz and $U_{t+1} \sim p_{\phi_t}$ where $(\phi, u) \mapsto p_{\phi}(u)$ is lsc

Proposition*

$(z^*, \Sigma^*) = (0, (1 - c_1 - c_\mu)\mathbf{I}_d)$ is steadily attracting and there exists $z_1^{j:\lambda}, \dots, z_k^{j:\lambda}$ at which $F^k(z^*, \Sigma^*, \cdot)$ is submersive.

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Consequence:

$\{(z_t, \Sigma_t)\}$ is irreducible and aperiodic.

2. Drift condition

$$V(z, \Sigma) = \alpha \|z\|^2 + \beta \|\Sigma\|$$

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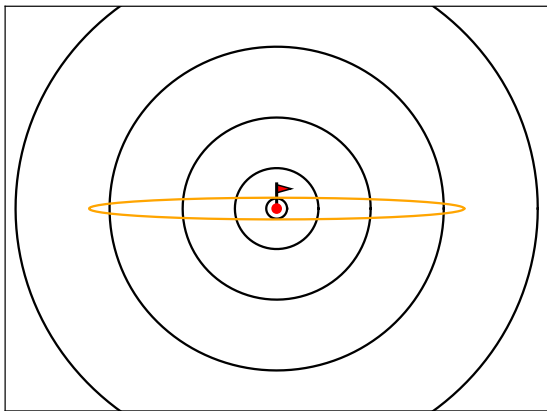
$$\mathbb{E}[\|z_1\|^2] \leq (1 - \varepsilon) \|z_0\|^2$$

Proposition

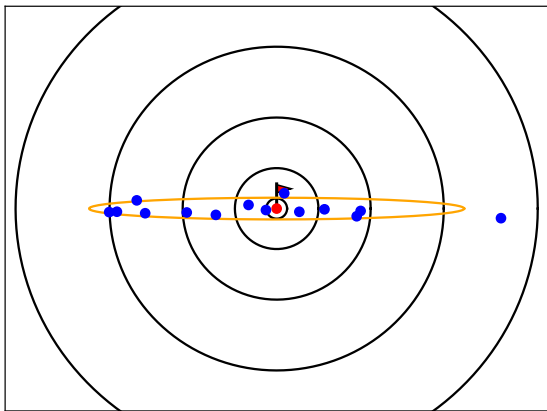
If (a) and (b) are true:

$$\exists K \text{ compact, } \mathbb{E}[V(z_1, \boldsymbol{\Sigma}_1)] \leq (1 - \varepsilon)V(z_0, \boldsymbol{\Sigma}_0) \quad \forall (z_0, \boldsymbol{\Sigma}_0) \notin K$$

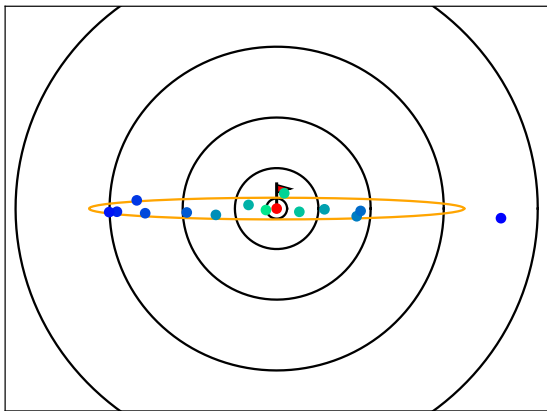
(a) When $\|\Sigma_0\| \gg 1 + \|z_0\|^2$



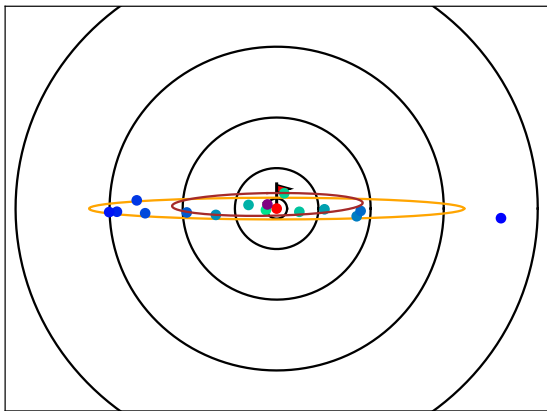
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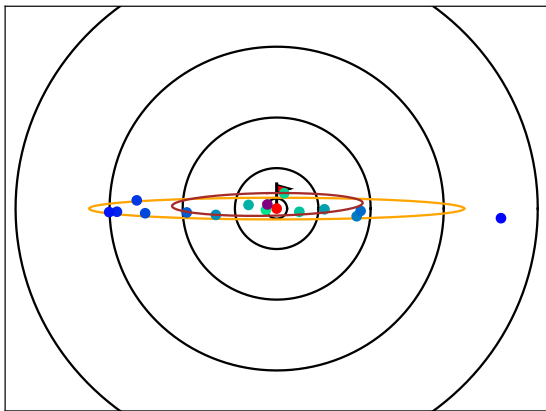
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Proposition*

When $f = \text{img}$ and $\|\Sigma_0\| \gg 1 + \|z_0\|^2$:

$$\mathbb{E}[\|\Sigma_1\|] \leq (1 - \varepsilon)\|\Sigma_1\|$$

(b) When $\|\Sigma_0\| \not\approx \|z_0\|^2$

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$$\text{normalization} = \text{increasing function}(\|m_{t+1} - m_t\|) \times \sqrt{\lambda_{\min}(\Sigma_1)}$$

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Proposition*

When $f = \text{img}(\text{target})$ and $\|\Sigma_0\| \not\gg \|z_0\|^2$:

$$\mathbb{E}[\|m_{t+1} - m_t\|] > \mathbb{E}\|\mathcal{N}\|$$

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Proposition*

When $f = \text{img}$ and $\|\Sigma_0\| \not\gg \|z_0\|^2$:

$$\mathbb{E}[\|m_{t+1} - m_t\|] > \mathbb{E}\|\mathcal{N}\|$$

If we choose the hyperparameters correctly:

$$\mathbb{E}[\text{normalization}] > 1$$

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Proposition*

When $f = \text{img}$ and $\|\Sigma_0\| \not\gg \|z_0\|^2$:

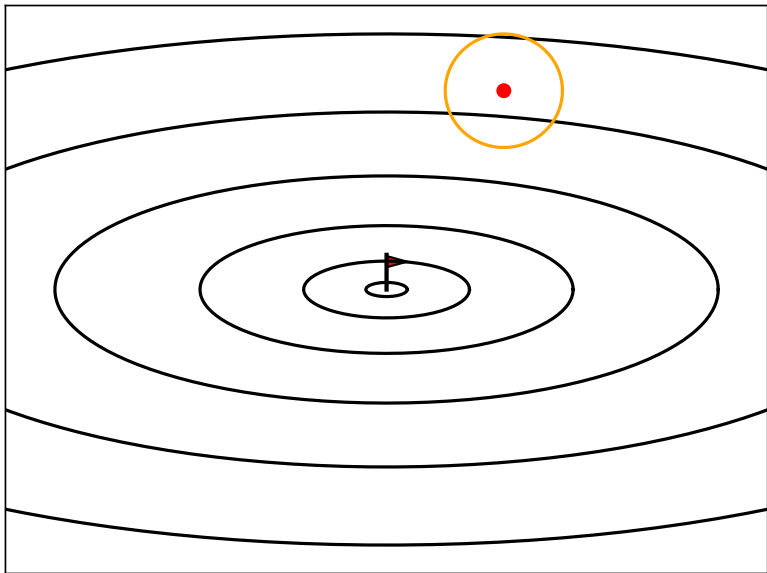
$$\mathbb{E}[\|m_{t+1} - m_t\|] > \mathbb{E}\|\mathcal{N}\|$$

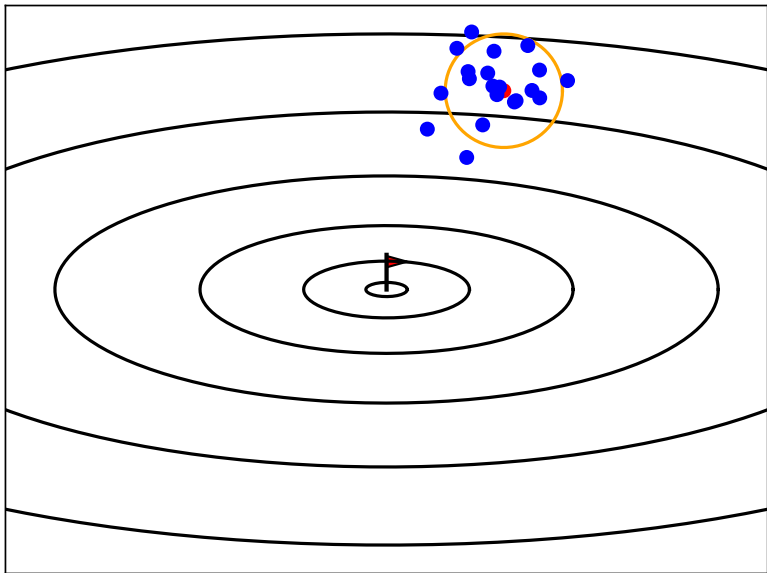
If we choose the hyperparameters correctly:

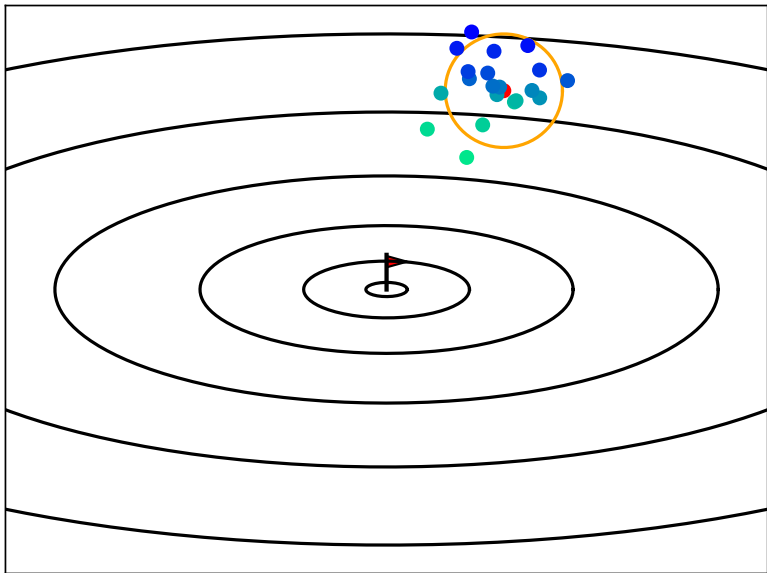
$$\mathbb{E}[\text{normalization}] > 1$$

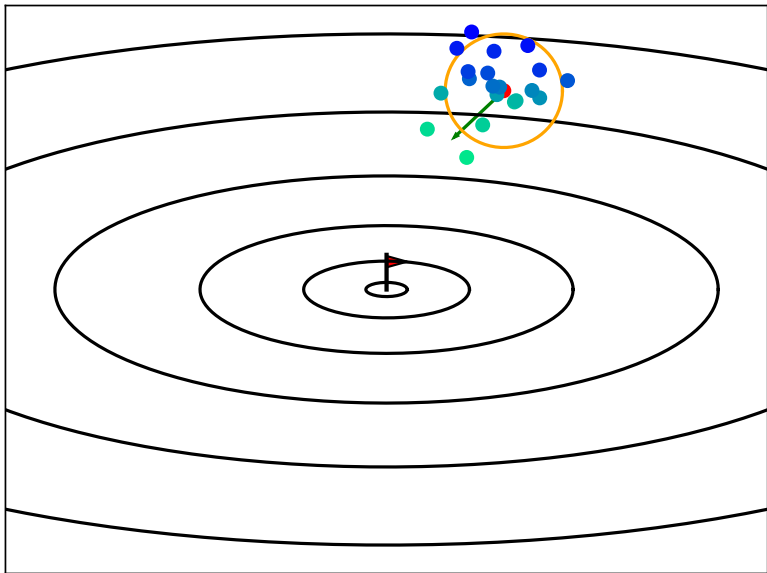
and

$$\mathbb{E}[\|z_1\|^2] \leq (1 - \varepsilon)\|z_0\|^2$$










Theorem*

When $f =$ 

$$\exists K \text{ compact, } \mathbb{E}[V(z_1, \Sigma_1)] \leq (1 - \varepsilon)V(z_0, \Sigma_0) \quad \forall (z_0, \Sigma_0) \notin K$$

Consequence:

$\{(z_t, \Sigma_t)\}_t$ is ergodic

Theorem*

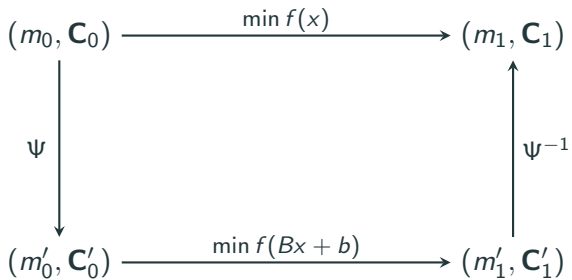
When $f = \text{img}$, CMA-ES converges linearly.

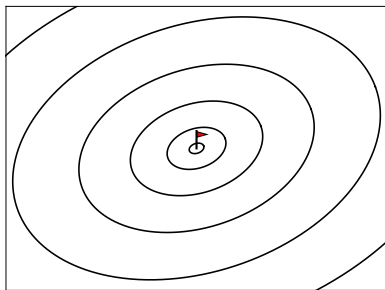
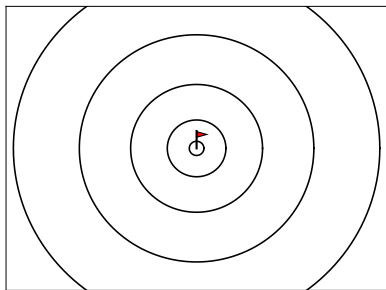
Theorem*

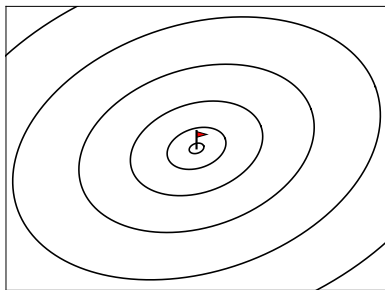
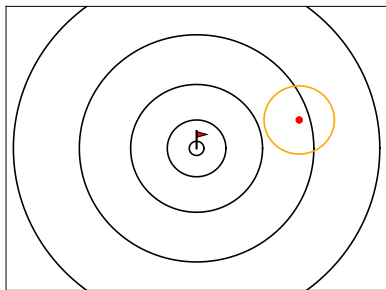
When $f = \text{[circular contour plot]}$, CMA-ES converges linearly.

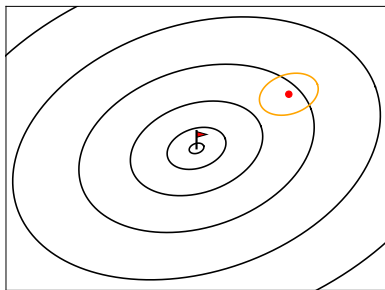
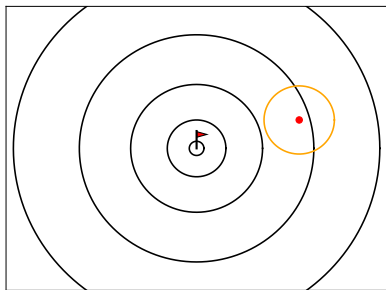
How to extend to $f = \text{[elliptical contour plot]}$?

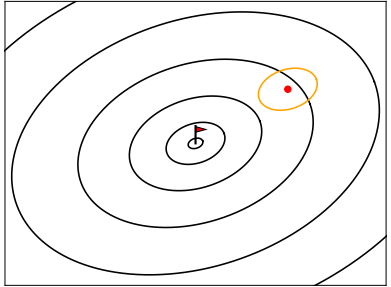
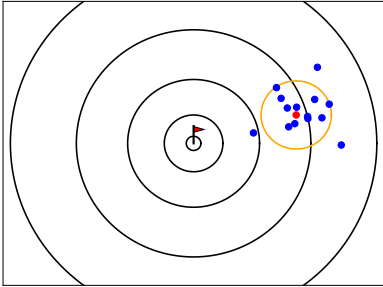
Affine-invariance

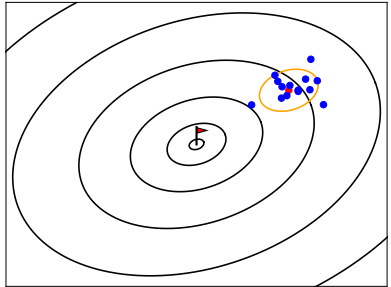
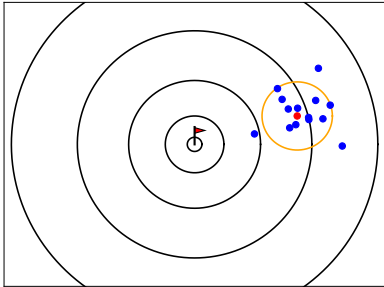


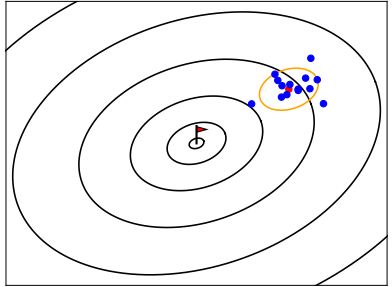
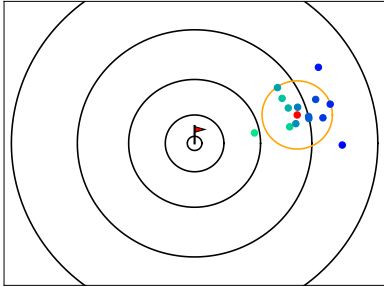


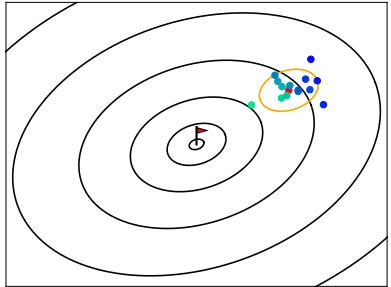
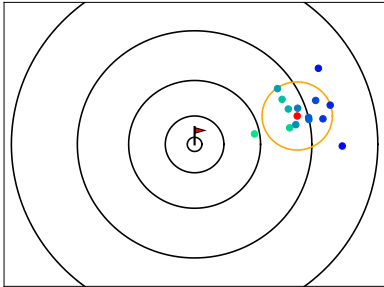


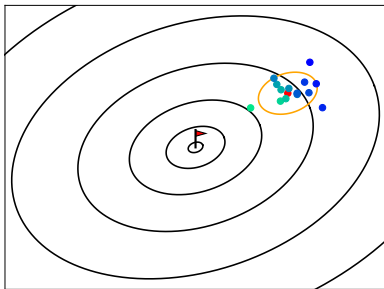
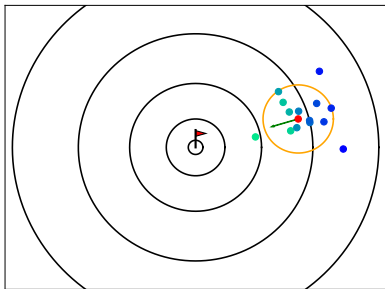


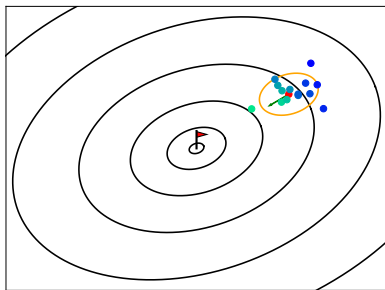
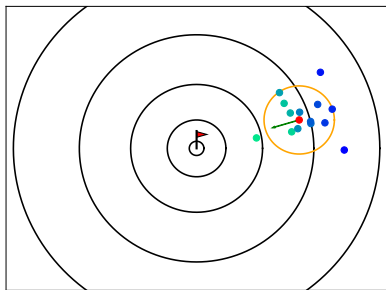


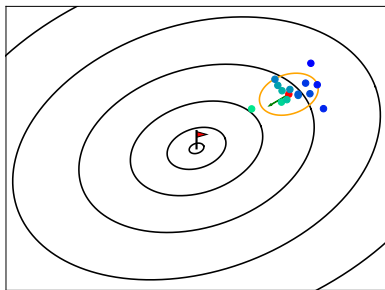
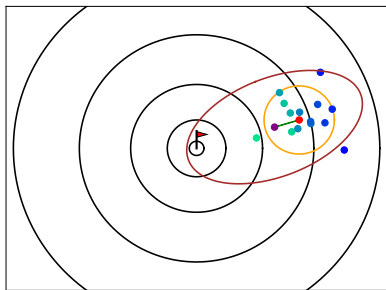


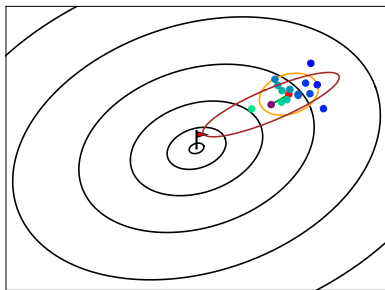
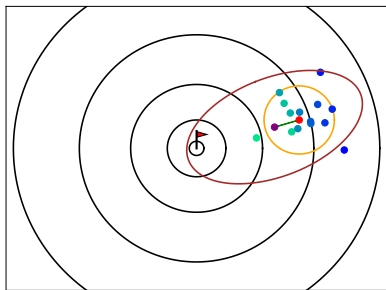












Theorem

CMA-ES is affine-invariant

Theorem

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Consequence

Theorem*

When $f =$ , *CMA-ES converges linearly.*

Theorem

CMA-ES is affine-invariant


Consequence

Theorem*

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(with the same convergence rate than )

Learning of the inverse Hessian

When $f =$ , we find

$$\lim_{t \rightarrow \infty} \mathbb{E} \left[\frac{\mathbf{C}_t}{\text{normalization}} \right] = \mathbf{I}_d$$

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Since  = $\text{Hessian}^{1/2} \times$ :

$$\begin{aligned} f = \text{img alt="elliptical contour plot" data-bbox="132 495 175 550"} &\Rightarrow \lim_{t \rightarrow \infty} \mathbb{E} \left[\frac{\mathbf{C}_t}{\text{normalization}} \right] = \text{Hessian}^{-1/2} \times \mathbf{I}_d \times \text{Hessian}^{-1/2} \\ &= \text{Hessian}^{-1} \end{aligned}$$

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Theorem*

CMA-ES learns the inverse Hessian of .

Conclusions

- CMA-ES converges linearly when $f =$ 
- The convergence rate does not depend on 
- The covariance matrix approximates the inverse Hessian

Thank you